BS ISO 7902-1:2013



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Hydrodynamic plain journal bearings under steadystate conditions — Circular cylindrical bearings Part 1: Calculation procedure

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Hydrodynamic plain journal bearings under steady-state conditions — Circular cylindrical bearings —

Part 1: Calculation procedure

Paliers lisses hydrodynamiques radiaux fonctionnant en régime stabilisé — Paliers circulaires cylindriques —

Partie 1: Méthode de calcul



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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

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The committee responsible for this document is ISO/TC 123, *Plain bearings*, Subcommittee SC 4, *Methods of calculation of plain bearings*.

This second edition cancels and replaces the first edition (ISO 7902-1:1998), which has been technically revised.

ISO 7902 consists of the following parts, under the general title *Hydrodynamic plain journal bearings under steady-state conditions* — *Circular cylindrical bearings*:

- Part 1: Calculation procedure
- Part 2: Functions used in the calculation procedure
- Part 3: Permissible operational parameters

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Hydrodynamic plain journal bearings under steady-state conditions — Circular cylindrical bearings —

Part 1: Calculation procedure

1 Scope

This part of ISO 7902 specifies a calculation procedure for oil-lubricated hydrodynamic plain bearings, with complete separation of the shaft and bearing sliding surfaces by a film of lubricant, used for designing plain bearings that are reliable in operation.

It deals with circular cylindrical bearings having angular spans, Ω , of 360°, 180°, 150°, 120°, and 90°, the arc segment being loaded centrally. Their clearance geometry is constant except for negligible deformations resulting from lubricant film pressure and temperature.

The calculation procedure serves to dimension and optimize plain bearings in turbines, generators, electric motors, gear units, rolling mills, pumps, and other machines. It is limited to steady-state operation, i.e. under continuously driven operating conditions, with the magnitude and direction of loading as well as the angular speeds of all rotating parts constant. It can also be applied if a full plain bearing is subjected to a constant force rotating at any speed. Dynamic loadings, i.e. those whose magnitude and direction vary with time, such as can result from vibration effects and instabilities of rapid-running rotors, are not taken into account.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3448, Industrial liquid lubricants — ISO viscosity classification

ISO 7902-2:1998, Hydrodynamic plain journal bearings under steady-state conditions — Circular cylindrical bearings — Part 2: Functions used in the calculation procedure

ISO 7902-3, Hydrodynamic plain journal bearings under steady-state conditions — Circular cylindrical bearings — Part 3: Permissible operational parameters

3 Basis of calculation, assumptions, and preconditions

3.1 The basis of calculation is the numerical solution to Reynolds' differential equation for a finite bearing length, taking into account the physically correct boundary conditions for the generation of pressure:

$$\frac{\partial}{\partial x} \left(h^3 \frac{\partial p}{\partial x} \right) + \frac{\partial}{\partial x} \left(h^3 \frac{\partial p}{\partial z} \right) = 6\eta \left(u_J + u_B \right) \frac{\partial h}{\partial x}$$
(1)

The symbols are given in <u>Clause 5</u>.

See References [1] to [3] and References [11] to [14] for the derivation of Reynolds' differential equation and References [4] to [6], [12], and [13] for its numerical solution.