

Third edition
2023-08

Calculation of load capacity of bevel gears —

Part 1: Introduction and general influence factors

*Calcul de la capacité de charge des engrenages coniques —
Partie 1: Introduction et facteurs généraux d'influence*



Reference number
ISO 10300-1:2023(E)

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO document should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 60, *Gears*, Subcommittee SC 2, *Gear capacity calculation*.

This third edition cancels and replaces the second edition (ISO 10300-1:2014), which has been technically revised.

The main changes are as follows:

- [Table 1](#) has been inserted in which only symbols and units used in this document are provided;
- [Table 2](#) has been inserted;
- [subclause 9.1](#) — boundary conditions for the calculation of the transverse load factors method B have been rearranged;
- Figure 3 — nomogram for the determination of the resonance speed, n_{E1} , for the mating solid steel pinion/solid wheel, with $c_\gamma = 20 \text{ N}/(\text{mm} \cdot \mu\text{m})$ (for bevel gears without offset only) has been removed;
- Figure 4 — dynamic factor, K_{v-C} , has been removed;
- Figure 5 — transverse load factors, $K_{H\alpha-B}$ and $K_{F\alpha-B}$ has been removed;
- Figure 6 — running-in allowance, y_α , of gear pairs with a tangential speed of $v_{mt2} > 10 \text{ m/s}$ has been removed;
- Figure 7 — running-in allowance, y_α , of gear pairs with a tangential speed of $v_{mt2} \leq 10 \text{ m/s}$ has been removed;
- [Figure A.6](#) — transverse path of contact has been newly inserted;

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- [Figure A.7](#) — general definition of length of contact lines for local geometry data has been newly inserted.

A list of all parts in the ISO 10300 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

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Introduction

When ISO 10300:2001 (all parts) became due for its first revision, the opportunity was taken to include hypoid gears, since previously the series only allowed for calculating the load capacity of bevel gears without offset axes. The former structure is retained, i.e. three parts of the ISO 10300 series, together with ISO 6336-5, and it is intended to establish general principles and procedures for rating of bevel gears. Moreover, ISO 10300 (all parts) is designed to facilitate the application of future knowledge and developments, as well as the exchange of information gained from experience.

Several calculation methods, i.e. A, B and C, are specified, which stand for decreasing accuracy and reliability from A to C because of simplifications implemented in formulae and factors. The approximate methods in ISO 10300 (all parts) are used for preliminary estimates of gear capacity where the final details of the gear design are not yet known. More detailed methods are intended for the recalculation of the load capacity limits when all important gear data are given.

ISO 10300 (all parts) does not provide an upgraded calculation procedure as a method A, although it would be available, such as finite element or boundary element methods combined with sophisticated tooth contact analyses.

On the other hand, by means of such a computer program, a new calculation procedure for bevel and hypoid gears on the level of method B was developed and checked. It is part of the ISO 10300 series as submethod B1. Besides, if the hypoid offset, a , is zero, method B1 becomes identical to the set of proven formulae of the former version of ISO 10300:2001 (all parts).

In view of the decision for ISO 10300 (all parts) to cover hypoid gears also, [Annex B](#) has been included in this document. Additionally, ISO 10300-2 is supplemented by a separate clause: “Gear flank rating formulae — Method B2”; as for ISO 10300-3, the former method B2, which uses the Lewis parabola to determine the critical section in the root and not the 30° tangent at the tooth fillet as method B1 does, is now extended by the AGMA methods for rating the strength of bevel gears and hypoid gears. It was necessary to present a new, clearer structure of the three parts, which is illustrated in [Figure 1](#).

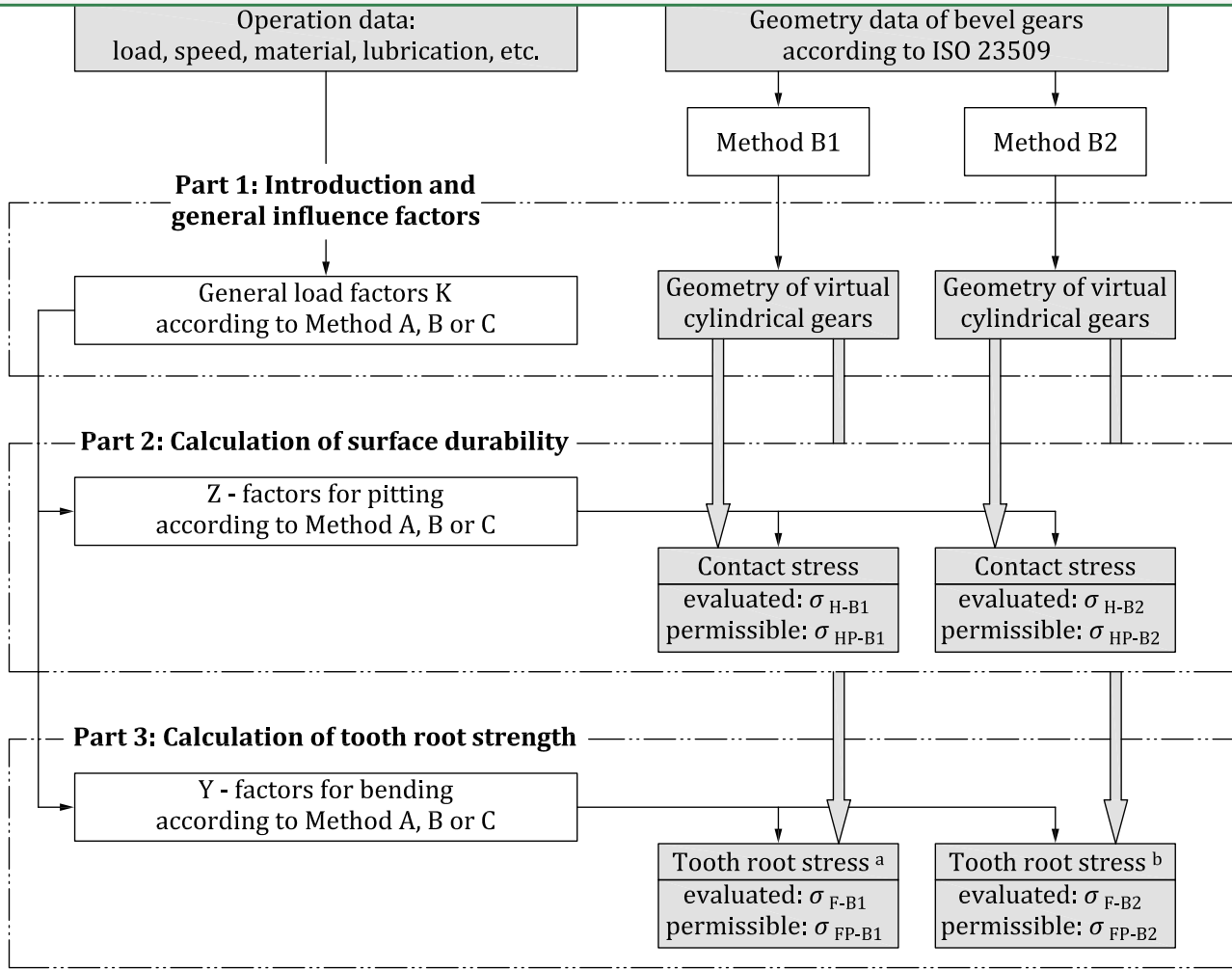
NOTE ISO 10300 (all parts) gives no preferences in terms of when to use method B1 and when to use method B2.

The procedures covered by ISO 10300 (all parts) are based on both testing and theoretical studies.

ISO 10300 (all parts) provides calculation procedures by which different gear designs can be compared. It is not meant to ensure the performance of assembled gear drive systems. It is intended for use by the experienced gear designer capable of selecting reasonable values for the factors in these formulae, based on knowledge of similar designs and on awareness of the effects of the items discussed.

NOTE Contrary to cylindrical gears, where the contact is usually linear, bevel gears are generally manufactured with profile and lengthwise crowning, i.e. the tooth flanks are curved on all sides and the contact develops an elliptical pressure surface. This is taken into consideration when determining the load factors by the fact that the rectangular zone of action (in the case of spur and helical gears) is replaced by an inscribed parallelogram for method B1 and an inscribed ellipse for method B2 (see [Annex A](#) for method B1 and [Annex B](#) for method B2). The conditions for bevel gears, different from cylindrical gears in their contact, are thus taken into consideration by the face and transverse load distribution factors.

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^a One set of formulae for both, bevel and hypoid gears.

^b Separate sets of formulae for bevel and for hypoid gears.

Figure 1 — Structure of calculation methods in ISO 10300 (all parts)