Second edition 2016-12-15

Road vehicles — Controller area network (CAN) —

Part 2: **High-speed medium access unit**

Véhicules routiers — Gestionnaire de réseau de communication (CAN) —

Partie 2: Unité d'accès au support à haute vitesse



ISO 11898-2:2016(E)

This is a preview of "ISO 11898-2:2016". Click here to purchase the full version from the ANSI store.



COPYRIGHT PROTECTED DOCUMENT

© ISO 2016, Published in Switzerland

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office Ch. de Blandonnet 8 • CP 401 CH-1214 Vernier, Geneva, Switzerland Tel. +41 22 749 01 11 Fax +41 22 749 09 47 copyright@iso.org www.iso.org

Contents Pag			
Fore	word		iv
Intr	oduction	v	
1		е	
_	-		
2		native references	
3	Term	s and definitions	1
4	Symb	ools and abbreviated terms	2
5	Funct	3	
	5.1	General	
	5.2	HS-PMA test circuit	
	5.3	Transmitter characteristics	
	5.4	Receiver characteristics	8
	5.5	Receiver input resistance	
	5.6	Transmitter and receiver timing behaviour	9
	5.7	5.7 Maximum ratings of V _{CAN H} , V _{CAN L} and V _{Diff}	
	5.8	Maximum leakage currents of CAN_H and CAN_L	12
	5.9	Wake-up from low-power mode	
		5.9.1 Overview	
		5.9.2 Basic wake-up	
		5.9.3 Wake-up pattern wake-up	
	5 10	5.9.4 Selective wake-up	
	5.10	Bus biasing	
		5.10.2 Normal biasing	
6	Confe	ormance	
_		formative) ECU and network design	
		formative) PN physical layer modes	
Bibl	iograph	V	30

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

The committee responsible for this document is ISO/TC 22, *Road vehicles*, Subcommittee SC 31, *Data communication*.

This second edition cancels and replaces the first edition (ISO 11898-2:2003), which has been technically revised, with the following changes:

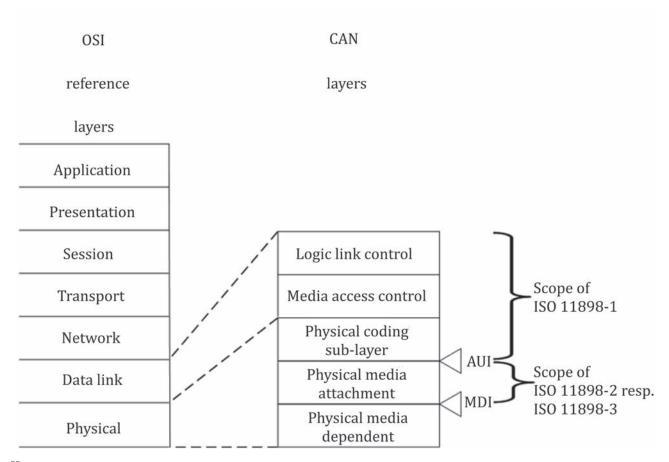
- max output current on CANH/CANL has been defined (Table 4);
- optional TXD timeout has been defined (Table 7);
- receiver input resistance range has been changed (<u>Table 10</u>);
- Bit timing parameters for CAN FD for up to 2 Mbps have been defined (<u>Table 13</u>);
- Bit timing parameters for CAN FD for up to 5 Mbps have been defined (<u>Table 14</u>);
- content of ISO 11898-5 and ISO 11898-6 has been integrated to ensure there is one single ISO Standard for all HS-PMA implementations;
- selective wake-up (formerly ISO 11898-6) CAN FD tolerance has been defined;
- wake-filter timings (formerly in ISO 11898-5) have been changed (Table 20)
- requirements and assumptions about the PMD sublayer have been shifted to <u>Annex A</u>, to clearly focus on the HS-PMA implementation.

A list of all parts in the ISO 11898 series can be found on the ISO website.

Introduction

ISO 11898 was first published as one document in 1993. It covered the CAN data link layer as well as the high-speed physical layer. In the reviewed and restructured ISO 11898 series, ISO 11898-1 and ISO 11898-4 defined the CAN protocol and time-triggered CAN (TTCAN) while ISO 11898-2 defines the high-speed physical layer, and ISO 11898-3 defined the low-speed fault tolerant physical layer.

<u>Figure 1</u> shows the relation of the Open System Interconnection (OSI) layers and its sublayers to ISO 11898-1, this document as well as ISO 11898-3.



Key

AUI attachment unit interface

MDI media dependant interface

OSI open system interconnection

Figure 1 — Overview of ISO 11898 specification series

The International Organization for Standardization (ISO) draws attention to the fact that it is claimed that compliance with this document may involve the use of a patent concerning the selective wake-up function given in 5.9.4.

ISO takes no position concerning the evidence, validity and scope of this patent right.

The holder of this patent right has assured ISO that he/she is willing to negotiate licenses under reasonable and non-discriminatory terms and conditions with applicants throughout the world. In this respect, the statement of the holder of this patent right is registered with ISO. Information may be obtained from the following:

ISO 11898-2:2016(E)

This is a preview of "ISO 11898-2:2016". Click here to purchase the full version from the ANSI store.

Audi AG	Elmos Semiconductor AG	Renesas Electronics Europe GmbH
August-Horch-Str.	Heinrich-Hertz-Str. 1	Arcadiastr. 10
85045 Ingolstadt	44227 Dortmund	40472 Düsseldorf
Germany	Germany	Germany
BMW Group	Freescale Semiconductor Inc.	Robert Bosch GmbH
Knorrstr. 147	6501 W. William Canon Drive	PO Box 30 02 20
80788 München	Austin, Texas	70442 Stuttgart
Germany	United States	Germany
Continental Teves AG & Co. oHG Guerickestr. 7 60488 Frankfurt am Main Germany	General Motors Corp. 30001 VanDyke, Bldg 2-10 Warren, MI 48090-9020 United States of America	STMicroelectronics Application GmbH Bahnhofstrasse 18 85609 Aschheim Dornach Germany
DENSO CORP.	NXP BV	Volkswagen AG
1-1, Showa-cho, Kariya-shi	High Tech Campus 60	PO Box 011/1770
Aichi-ken 448-8661	5656 AG Eindhoven	38436 Wolfsburg
Japan	The Netherlands	Germany

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights other than those identified above. ISO shall not be held responsible for identifying any or all such patent rights. ISO (www.iso.org/patents) maintains on-line databases of patents relevant to their standards. Users are encouraged to consult the databases for the most up to date information concerning patents.