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Information technology — Real time locating systems (RTLS) —

Part 62: High rate pulse repetition frequency Ultra Wide Band (UWB) air interface

*Technologie de l'information — Systèmes de localisation en temps réel
(RTLS) —*

*Partie 62: Interface aérienne ultra large bande (UWB) à impulsions
haute fréquence de répétition*

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Foreword

ISO (the International Organization for Standardization) and IEC (the International Electrotechnical Commission) form the specialized system for worldwide standardization. National bodies that are members of ISO or IEC participate in the development of International Standards through technical committees established by the respective organization to deal with particular fields of technical activity. ISO and IEC technical committees collaborate in fields of mutual interest. Other international organizations, governmental and non-governmental, in liaison with ISO and IEC, also take part in the work. In the field of information technology, ISO and IEC have established a joint technical committee, ISO/IEC JTC 1.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of the joint technical committee is to prepare International Standards. Draft International Standards adopted by the joint technical committee are circulated to national bodies for voting. Publication as an International Standard requires approval by at least 75 % of the national bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO and IEC shall not be held responsible for identifying any or all such patent rights.

ISO/IEC 24730-62 was prepared by Joint Technical Committee ISO/IEC JTC 1, *Information technology*, Subcommittee SC 31, *Automatic identification and data capture techniques*.

ISO/IEC 24730 consists of the following parts, under the general title *Information technology — Real time locating systems (RTLS)*:

- *Part 1: Application program interface (API)*
- *Part 2: Direct Sequence Spread Spectrum (DSSS) 2,4 GHz air interface protocol*
- *Part 5: Chirp spread spectrum (CSS) at 2,4 GHz air interface*
- *Part 21: Direct Sequence Spread Spectrum (DSSS) 2,4 GHz air interface protocol: Transmitters operating with a single spread code and employing a DBPSK data encoding and BPSK spreading scheme*
- *Part 22: Direct Sequence Spread Spectrum (DSSS) 2,4 GHz air interface protocol: Transmitters operating with multiple spread codes and employing a QPSK data encoding and Walsh offset QPSK (WOQPSK) spreading scheme*
- *Part 61: Low rate pulse repetition frequency Ultra Wide Band (UWB) air interface*
- *Part 62: High rate pulse repetition frequency Ultra Wide Band (UWB) air interface*

Introduction

This series of standards defines one Air Interface Protocol for Real Time Locating Systems (RTLS) for use in asset management and is intended to allow for compatibility and to encourage interoperability of products for the growing RTLS market.

This document, the high rate pulse repetition frequency (HRP) UWB Air Interface Protocol, establishes a technical standard for Real Time Locating Systems that operate at an internationally available UWB frequency bands and that are intended to provide accurate location (e.g. within some tens of centimetres) with frequent updates (for example, every second).

Real Time Locating Systems are wireless systems with the ability to locate the position of an item anywhere in a defined space (local/campus, wide area/regional, global) at a point in time that is, or is close to, real time. Position is derived by measurements of the physical properties of the radio link.

Conceptually there are four classifications of RTLS:

- Locating an asset via satellite - requires line-of-sight - accuracy to 10 meters
- Locating an asset in a controlled area, e.g., warehouse, campus, airport - area of interest is instrumented - accuracy to 3 meters
- Locating an asset in a more confined area - area of interest is instrumented - accuracy to tens of centimetres
- Locating an asset over a terrestrial area using a terrestrial mounted receivers over a wide area, cell phone towers for example – accuracy 200 meters

With a further two methods of locating an object which are really RFID rather than RTLS:

- Locating an asset by virtue of the fact that the asset has passed point A at a certain time and has not passed point B
- Locating an asset by virtue of providing a homing signal whereby a person with a handheld can find an asset

Method of location is through identification and location, generally through multilateration

- Types
 - Time of Flight Ranging Systems
 - Amplitude Triangulation
 - Time Difference of Arrival (TDOA)
 - Cellular Triangulation
 - Satellite multilateration
 - Angle of Arrival

This standard defines the air interface protocol needed for the creation of an RTLS system using HRP UWB which is a physical layer UWB signalling mechanism (based on standard IEEE 802.15.4a UWB) and employing high rate pulse repetition frequencies (PRF) 16 MHz or 64 MHz, and a combination of burst position modulation (BPM) and binary phase-shift keying (BPSK).