

# SPECIFICATION

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## **Robotics — Collaborative applications — Test methods for measuring forces and pressures in human-robot contacts**

*Robotique — Applications collaboratives — Méthodes d'essai pour  
mesurer les forces et les pressions dans les contacts homme-robot*



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## Foreword

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This document was prepared by Technical Committee ISO/TC 299, *Robotics*.

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## Introduction

All testing methods specified in this document represent the latest state-of-the-art in the research field of contact measurement and testing with robots made for biomechanically safe interactions with humans. The procedures described in this document have been developed with a focus on practical applicability and several examples have been included in the annexes to this effect. The intended users of the document include integrators, operators, and users of collaborative applications as well as manufacturers of pressure-force measurement devices (PFMD).

The purpose of this document is to facilitate the application of other standards such as ISO 10218-2:—<sup>1)</sup>, Annex N, robot applications and robot cells integration (based on RIA TR R15.806:2018) or ISO/TS 15066.

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1) Under preparation. Stage at the time of publication: ISO/FDIS 10218-2:2023.